

Demonstration of the Spatial Sensitivity of a Compact HD-DOT System Using a Retinotopy Paradigm

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Methods

Outline

With large arrays of spatially distributed near-infrared sources and photodetectors, Diffuse Optical Tomography (DOT) systems have been used to image the spatially varying distribution of the concentrations of chromophores such as oxy- and deoxyhemoglobin. Traditional DOT systems rely on fiber optic cables to carry optical signals to and from the imaged tissue. As the number of channels increases, the weight and size of the optical fibers limit both the comfort and practical utility of such systems in clinical use.

We have developed a compact, multi-channel and multi-wavelength continuous wave DOT imaging system that does not use fiber optic cables [1]. To validate the performance of our system in vivo, we performed retinotopic mapping of the visual cortex as previously described by fMRI studies [2] and other HD-DOT systems [3,4].

The results presented here replicate earlier work with a fiber-based HD-DOT system [4] and demonstrate that similar spatial mapping of the human visual cortex is achievable in a compact, easy-to-use HD-DOT device.

Hardware System

- High-density arrangement: 10x18 (sources x detectors) on rigid-flex circuit boards (Fig. 1a).
- Five, time-encoded, amplitude-modulated VCSELs within each source optode operate at five wavelengths (688-850nm)
- Each detector optode contains a single silicon photodiode with 7.0 mm² detection area

Retinotopy Experimental Protocol

- Two healthy subjects enrolled and provided informed consent (WIRB Study # 1132591)
- Subjects were seated approximately 30 inches from a computer screen; the screen was height adjusted for each subject
- A sensor was applied to the back of each subject's head just above the inion to maximize coverage of the primary visual cortex
- Rotating Checkerboard Wedge Stimulus
 - 60° wedge width with alternating (10Hz) checkboard pattern •
 - Wedges rotate at 10^o steps/sec (one full rotation = 36s)





- Detected continuous-wave signals demodulated via a synchronous detection demodulation scheme
- Overlapping source-detector distances range from 13-87mm
- 180 channels per wavelength collected at 5Hz frame-rate. Acquired data is digitized, processed, and transmitted to a laptop via Ethernet connection for post-processing (fiber-free interface)
- Dynamic range of over 140 dB (NEP $\approx 0.14 \text{pW}/\sqrt{hz}$)

(a)



Figure 1: DOT Sensor array and example data from a human subject. (a) Photo of the high density prototype DOT sensor array containing 10 sources (yellow) and 18 detectors (blue). Green lines show all measurement pairs ranging from 13-87mm. (b) Example optical signal intensities and phase as a function of source-detector distance

- 10 full revolutions of the wedge stimulus presented with rotation either *clockwise* (CW) or *counterclockwise* (CCW)
- Subjects were instructed to maintain focus on the crosshairs at the center of the monitor at all times
- Subjects were seated in a dark room and wore passive noise canceling headphones to minimize distraction

Data Processing and HbO & HbR reconstruction

- Data from all optode pairs bandpass filtered (0.02Hz-0.5Hz) and downsampled to 1Hz, giving one sample per stimulus wedge position
- Signals with low SNR were removed from the analysis
- Rytov approximation, expressed as $y = -\log(\phi/\phi_0) = Ax$, was used for estimation of voxelized Δ HbO and Δ HbR perturbations, where:
 - ϕ is the measured light intensities (*e.g.* Fig. 1b) at any given time point
 - ϕ_0 is the mean of the signals across all stimulus presentations
 - x is a vector of the changes in HbO and HbR for all voxels in the imaging volume
 - A is the chromophore sensitivity matrix for the specific sensor-array geometry constructed according to [3]. Finite-element modeling in a twolayered slab model was performed using NIRFAST to generate Green's functions for the sensitivities of each source and detector for all wavelengths [5]
- Moore-Penrose generalized inverse [4] was used for the estimation of Δ HbO and Δ HbR perturbation images, $x = A^{\#}y$, by minimizing the objective function: $\min\{\|(y - Ax)\|_2^2 + \alpha \|Lx\|_2^2\}$, where $A^{\#} = L^{-1}A^T(A^TA + \alpha I)^{-1}$, $L = \sqrt{diag(A^TA) + \beta}$, and α and β represent regularization values [3]
- Measurements were processed into 2-D images of the brain layer with 2mm pixel size

Polar Angle Mapping and Response Strength

- Δ HbO temporal responses were mapped to visual polar angle by estimating the phase-delay of the oscillations for each pixel in the imaging field
- Briefly, the Discrete Fourier Transform at the visual stimulus rotation frequency (f_{stim}=0.0278Hz) was computed:

$$X_{f_{stim}} = \sum_{n=0}^{I} x[n] e^{-i2\pi \left(\frac{1}{36}\right)n}$$

- The angle of the complex estimate was mapped to the polar angle of the rotating wedge stimulus at the time of the lag [including a delay to account for the neurovascular coupling delay]
- The magnitude of the estimate was mapped to provide an estimate of the strength of the measured response to the rotating stimulus



Figure 2: Example of mapping polar angle from the Δ HbO temporal trend. Phase lag and magnitude estimated from projection onto complex sinusoid









Results



Figure 3: Activation images and hemoglobin temporal trends. (a) Δ HbO activation images for five different wedge positions. As expected, activation is mapped to visual cortex positions contralateral and inverted to the presented wedge position. (b) Temporal trends of Δ HbO (red), Δ HbR (blue), and Δ HbT (green) from a randomly selected pixel in the imaging field. Trend covers 7 cycles of the rotating wedge (dashed lines indicate the start of each revolution). The trends show the strong periodic nature of the Δ HbO activation



Figure 4: Temporal trends of Δ HbO for four cycles of the rotating wedge shown for three different spatial positions in the imaging field. All three locations are strongly periodic with the stimulus presentation, but each location is maximally stimulated at different times. The times correspond to the wedge position that the cortical tissue is maximally sensitive to at each location

References

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Figure 5: Polar Angle mapping in Subjects 1 and 2. For each subject, three different measurements are shown with the dates of the measurements indicated. Two of the three measurements were taken in the same recording session with one recording done using the clockwise rotating stimulus (CW) and the other using a counter-clockwise (CCW) stimulus. For each measurements, we present the polar angle map and the correlation strength image. The Correlation Strength plots highlight the strong activation of the two hemispheres. The polar angle map of the HbO response shows the mapping of polar angle across the entire imaging field. Polar angle maps are similar within a subject but appear qualitatively different between subjects 1 and 2

Discussion and Conclusions

- We have demonstrated that our compact, non fiber-optic HD-DOT system is capable of generating detailed maps of the activation of primary visual cortex to stimuli that vary across the spatial visual field, enabled by a high-density optode grid and measurements at multiple overlapping source-detector distances
- Across subjects, we see similarities with each hemisphere responding to similar polar angles. However, notable differences in the fine structure of the maps exist. These differences may reflect differences in the folding of the cortical surfaces
- Within an individual subject, the maps of the stimulus angle appear highly repeatable across measurements taken several months apart as well as using different stimulations paradigms (Clockwise vs Counter-clockwise)
- Mapping the correlation strength may help visualize the midline between hemispheres which could enable better image registration for comparison of repeat, independent measurements
- These results demonstrate that our wearable HD-DOT system is capable of replicating cortical stimulus mapping studies that have





